# The efficient evaluation of multi-normal distribution functions

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- 1 Orthant & orthoscheme probabilities
- 1.1 Non-centred orthant probability

$$P_m(\mu, R) = \Pr\{x_1 \ge 0, \dots, x_m \ge 0\}$$
 (1)  
 $= \int_0^\infty \cdots \int_0^\infty \phi_m(x; \mu, R) \ dx_1 \cdots dx_m$ 

$$x=(x_1,\ldots,x_m)'\sim N_m(\mu,R)$$

R: Positive-definite correlation matrix

 $P_m(0,R)$  : centred orthant probability

ullet Multi-normal distribution function $F_m(c;\mu,R) = \Pr\{x_i \leq c_i, \ 1 \leq i \leq m\} \ = \Pr\{-x_i + c_i \geq 0, \ 1 \leq i \leq m\} \ = P_m(-\mu + c,R)$ 

### 1.2 orthoscheme probability $\tilde{R}$ : tridiagonal

$$ilde{R} = egin{pmatrix} 1 & 
ho_{12} & 0 & \cdots & 0 \ 
ho_{21} & 1 & 
ho_{23} & \cdots & 0 \ dots & \ddots & \ddots & \ddots & dots \ dots & \ddots & \ddots & \ddots & dots \ 0 & \cdots & 
ho_{m-1,m-2} & 1 & 
ho_{m-1,m} \ 0 & \cdots & 0 & 
ho_{m,m-1} & 1 \end{pmatrix}$$

 $P_m(\mu, \tilde{R})$ : non-centred orthoscheme probability  $P_m(0, \tilde{R})$ : centred orthoscheme probability

### **OUTLINE OF TODAY'S TALK**

- 1) Quick & accurate evaluation of  $P_m(\mu, ilde{R})$
- 2) Expressing a non-centred orthant probability as a linear combination of n-c orthoscheme probabilities

- 2 Recursive evaluation of non-centred orthoscheme probabilities
- 2.1 Cholesky decomposition

$$egin{aligned} ilde{R} &= egin{pmatrix} 1 & 
ho_{12} & 0 & \cdots & 0 \ 
ho_{21} & 1 & 
ho_{23} & \cdots & 0 \ dots & dots & \ddots & \ddots & dots & dots \ dots & dots & dots & \ddots & dots & dots \ dots & dots & dots & dots & dots & dots & dots \ dots & dots &$$

 $b_{11} = 1, b_{21}, b_{22}, \ldots$  are sequentially determined.

ullet Variable transformation With  $ilde{R} = BB'$  $x = Bz + \mu \sim N_m(\mu, ilde{R})$  $z \sim N_m(0, I_m)$ 

$$egin{aligned} x_1 &= oldsymbol{z}_1 + \mu_1 \ x_2 &= b_{21} oldsymbol{z}_1 + b_{22} oldsymbol{z}_2 + \mu_2 \ x_3 &= b_{32} oldsymbol{z}_2 + b_{33} oldsymbol{z}_3 + \mu_3 \ &oldsymbol{i} \ x_i &= b_{i,i-1} oldsymbol{z}_{i-1} + b_{ii} oldsymbol{z}_i + \mu_i \ &oldsymbol{i} \ x_m &= b_{m,m-1} oldsymbol{z}_{m-1} + b_{mm} oldsymbol{z}_m + \mu_m \end{aligned}$$

$$egin{aligned} P_m(\mu, ilde{R}) &= \Pr\{x_1 \geq 0, \dots, x_m \geq 0\} \ &= \Pr\{oldsymbol{z}_1 + \mu_1 \geq 0, \ b_{21}oldsymbol{z}_1 + b_{22}oldsymbol{z}_2 + \mu_2 \geq 0, \dots \ b_{i,i-1}oldsymbol{z}_{i-1} + b_{ii}oldsymbol{z}_i + \mu_i \geq 0, \dots \ b_{m,m-1}oldsymbol{z}_{m-1} + b_{mm}oldsymbol{z}_m + \mu_m \geq 0\} \end{aligned}$$

$$=\int_{-\mu_1}^\infty \phi(z_1) dz_1 \int_{(-b_{21}z_1-\mu_2)/b_{22}}^\infty \phi(z_2) dz_2 \ \cdots \int_{(-b_{i,i-1}z_{i-1}-\mu_i)/b_{ii}}^\infty \phi(z_i) dz_i \ \cdots \int_{(-b_{m,m-1}z_{m-1}-\mu_m)/b_{mm}}^\infty \phi(z_m) dz_m$$

2.2 **Recursive** integration formulae

$$f_{m-1}(m{z}) = \int_{(-b_{m,m-1}m{z}-\mu_m)/b_{mm}}^{\infty} \phi(t) dt,$$
 (2)

$$egin{aligned} f_{i-1}(m{z}) &= \int_{(-b_{i,i-1}m{z}-\mu_i)/b_{ii}}^{\infty} f_i(t) \phi(t) dt, \ &2 \leq i \leq m-1, \end{aligned}$$

$$P_m(\mu, ilde{R}) = \int_{-\mu_1}^\infty f_1(z)\phi(z)dz.$$
 (4)

- Evaluate (2) over a grid of points, and repeat (3).
- We can delete  $f_i(z)$  after obtaining  $f_{i-1}(z)$ .
- Computational time  $\propto m \cdot G$  (G: #{grid points}).



Figure 1. Recursive integration method

$$f_{i-1}(z) = \int_{(-\mu_i - b_{i,i-1}z)/b_{ii}}^\infty f_i(t) \phi(t) dt \ (f_i(t) ext{ is defined at grid points } \dots, t_j, t_{j+1}, \dots$$

## 2.3 Comparisons with known exact values $ho_{i,i-1}\equiv ho=-1/2:~P_m(0, ilde{R})=1/(m+1)!$

Table 1. Centred orthoscheme probabilities

$\overline{G}$	m=5	m = 10		m = 50		
32	0.001388885	0.2502	$ imes 10^{-7}$			
64	0.0013888888	0.25051	$ imes 10^{-7}$			
<b>128</b>	0.0013888889	0.250520	$ imes 10^{-7}$	0.63	$ imes 10^{-68}$	
<b>256</b>		0.25052105	$5 imes 10^{-7}$	0.6440	$ imes 10^{-68}$	
<b>512</b>		0.25052108	$8 \times 10^{-7}$	0.64466	$ imes 10^{-68}$	
<b>1024</b>				0.644694	$ imes 10^{-68}$	
<b>2048</b>				0.6446958	$ imes 10^{-68}$	
4096				0.64469596	$ imes 10^{-68}$	
exact	0.0013888889	0.25052108	$8 imes 10^{-7}$	0.64469596	$ imes 10^{-68}$	
+	G: number of grid points					
	Computational time is negligible.					

3 Expressing an orthant probability as a linear combination of orthoscheme probabilities

### 3.1 Theorem

Any non-centred orthant probability can be expressed as a linear combination of at most (m-1)!non-centred orthoscheme probabilities:

$$P_m(\mu,R) = \sum_{s=1}^{(m-1)!} c_s P_m(\mu^{(s)}, ilde{R}^{(s)})$$
 (5)

 $ilde{m{R}}^{(s)}$ : tridiagonal $c_s=+1 ext{ or } -1 ext{ or } 0.$ 

### **Outline of the proof**

ullet Variable transformation from x to z

$$egin{aligned} R &= A'A, \quad A = (a_1, \dots, a_m) \ a_i'a_i &= 1, \quad a_i'a_j = 
ho_{ij} \ (i 
eq j) \ x &= A'z \sim N_m(\mu, R) \ z \sim N_m(\mu_z, I_m), \quad \mu_z = (A')^{-1}\mu \ P_m(\mu, R) &= \Pr\{x_i \geq 0, \ 1 \leq i \leq m\} \end{aligned}$$

$$\Gamma_{m}(\mu, \mathbf{R}) = \Pr\{x_{i} \geq 0, \ 1 \leq i \leq m\} \\
= \Pr\{a_{i}'z \geq 0, \ 1 \leq i \leq m\} \\
= \Pr\{z \in Q\}.$$
(6)

• Polyhedral cone

$$\boldsymbol{Q} = \{ \boldsymbol{z} \colon a_i' \boldsymbol{z} \ge 0, \ 1 \le i \le m \}$$
(7)

• Hyper plane

$$egin{aligned} H_i &= \{z \colon a_i'z = 0\}, \quad 1 \leq i \leq m \ a_i \colon ext{Normal vector to } H_i \ a_i'a_j &= 
ho_{ij} \ (i 
eq j) \ ext{Edge vector} \ V &= (v_1, \dots, v_m) \ &= (A')^{-1} \ a_i'v_k &= 0 \ (k 
eq i) \ &\downarrow \ v_k \in H_i \ ext{Figure 2. Example } (m = 3) \end{aligned}$$

A trihedral cone

• Orthoscheme cone

$$a_i'a_j = \rho_{ij} = 0, \quad |i - j| > 1$$
 (8)

 $P_m(\mu, R)$  corresponding to these orthoscheme cones can be easily evaluated by the recursive procedure.

- The theorem is proved by showing that any polyhedral cone can be dissected into at most (m-1)! orthoscheme cones.
- For the detail, see

Miwa, T., Hayter, A. J. and Kuriki, S. (2003?). The evaluation of general non-centred orthant probabilities. *Submitted for publication*.

### 3.2 Example: Dissectioning a trihedral cone



 $egin{aligned} Q^{(2)}: ext{ edge vectors } & v_1, \ p, \ v_3 \ & ext{normal vectors } & a_1, \ a_2, \ ilde{a}_3 \end{aligned} \ Q^{(3)}: ext{ edge vectors } & v_1, \ v_2, \ p \ & ext{normal vectors } & a_1, \ ilde{a}_2, \ a_3 \end{aligned}$ 

### 3.3 Comparisons with known exact values Known exact values: $P_m(0, R) = 1/(m + 1)$ (1) $\rho_{ij} \equiv \rho = 1/2$ (#{cones} = 40320 = 8!) (2) $R^{-1} = \{\rho^{ij}\}$ is tridiagonal; $\rho^{ii} = 1$ , $\rho^{i,i+1} = -1/2$ . (#{cones} = 323 < 8!)

Table 2. Centred orthant probabilities (m = 9)

G	$ ho_{ij}=1/2$	$ ho^{i,i+1}=-1/2$			
32	0.0999751100 (12.61)	$0.1000142803 \ (0.08)$			
64	0.0999990004 (23.01)	$0.1000006159 \ (0.16)$			
128	0.0999999489 (44.02)	$0.100000321 \ (0.30)$			
<b>256</b>	0.0999999968 (87.49)	$0.100000020 \ (0.59)$			
512	$0.0999999998 \ (172.12)$	$0.100000001 \ (1.18)$			
exact	0.100000000	0.100000000			
†	G: $\#\{\text{grid points}\}$ . CPU time in (sec).				
	Run on a PC with Pentium <sup><math>\mathbb{R}</math></sup> 4 (1.5 GHz).				

- 4 Discussions
- 4.1 Applications: many
- 4.2 Remaining problems
  - In the worst case where (m-1)! cones are needed,

Computational time  $\propto m \cdot G \times (m-1)! = m! \cdot G$ .

 Table 3. Computational time for various m 

  $(
ho_{ij} \equiv 
ho = 1/2; \, G = 128 \, {
m grid points})$  

 m 5 6 7 8 9 10 

 m 5 6 7 8 9 10 

 CPU time (sec)
 0.01 0.08 0.58 4.76 44.02 450.46 

• If the correlation matrix R is singular, we have to evaluate  $\Pr\{z \in \mathbb{Q}\}$  where  $\mathbb{Q}$  is a polyhedron.

- **5** Historical remarks
- Schläfli (1858):

$$P_m(\mathbf{0},R) = \sum_{s=1}^{m!} c_s P_m(\mathbf{0}, ilde{R}^{(s)})$$

• Abrahamson (1964):

$$P_4(m{0},R) = \sum_{s=1}^{6=3!} c_s P_4(m{0}, ilde{R}^{(s)})$$

• Miwa et al. (2003?):

$$P_m(m{\mu},R) = \sum_{s=1}^{(m-1)!} c_s P_m(m{\mu}^{(s)}, ilde{R}^{(s)})$$

 $\tilde{R}^{(s)}$ : tridiagonal

### 6 Comparison with Monte Carlo methods

 Table 4. Centred orthant probabilities

with known exact probabilities ( $ho_{ij} \equiv 
ho = 0.5, \, \mu_i = 0.0$ )

	Our procedure				Genz's procedure			
	G = 16		G = 128		$\epsilon = 0.001$		$\epsilon = 0.0001$	
	$\mathbf{CPU}$	abs	CPU	abs	CPU	abs	CPU	abs
	$\mathbf{time}$	error	$\mathbf{time}$	error	$\mathbf{time}$	error	$\mathbf{time}$	error
$\boldsymbol{m}$	(sec)		(sec)		(sec)		(sec)	
5	0.00	2.1e-6	0.01	<b>1.4e-9</b>	0.68	$\mathbf{2.1e}\textbf{-4}$	<b>59.67</b>	<b>3.5e-5</b>
6	0.01	<b>3.5e-6</b>	0.08	$\mathbf{2.0e}\text{-}10$	0.74	$\mathbf{2.7e}\text{-}4$	97.86	$\mathbf{2.2e}\text{-}5$
7	0.07	<b>9.2e-6</b>	0.58	<b>5.8e-9</b>	1.14	<b>3.5e-4</b>	100.22	$\mathbf{2.7e}\text{-}5$
8	0.58	<b>5.7e-5</b>	4.76	<b>2.1e-8</b>	1.10	$\mathbf{2.5e-4}$	97.70	<b>3.3e-5</b>
9	5.35	<b>1.6e-4</b>	<b>44.02</b>	<b>5.1e-8</b>	1.55	$\mathbf{2.8e-4}$	137.62	<b>3.6e-5</b>
10	53.99	<b>3.5e-4</b>	<b>450.46</b>	<b>1.0e-7</b>	1.39	$\mathbf{2.1e-4}$	124.86	$\mathbf{2.3e}\textbf{-}5$
20					1.85	$\mathbf{2.8e}\textbf{-4}$	198.90	<b>3.3e-5</b>

Genz, A. (1992). Numerical computation of multivariate normal probabilities. J. Comput. Graph. Statist., 1, 141–149.